# Project 11 Brownian Motion

Lect 22, Wednesday 8 April

# **11.1** Random elements of $C[0,\infty)$

Suppose  $\{X_t : t \in \mathbb{R}^+\}$  is a process with continuous sample paths. That is, for each fixed  $\omega$  the sample path  $X(\omega, \cdot)$  is a member of  $C[0, \infty)$ , the set of all continuous real functions (not necessarily bounded) on  $\mathbb{R}^+$ . Equip  $C[0, \infty)$ with its **cylinder sigma-field**  $\mathbb{C}$ , which is defined as the smallest sigmafield on  $C[0, \infty)$  for which each coordinate map  $\pi_t$  is  $\mathbb{C} \setminus \mathcal{B}(\mathbb{R})$ -measurable. Then  $\omega \mapsto X(\omega, \cdot)$  is an  $\mathcal{F} \setminus \mathbb{C}$ -measurable map from  $\Omega$  into  $C[0, \infty)$ —see Problem [1]. Equip  $C[0, \infty)$  with its metric for uniform convergence on compacta,

$$d(x,y) = \sum_{k \in \mathbb{N}} 2^{-k} \min(1, \sup_{0 \le t \le k} |x(t) - y(t)|)$$

- (i) Show that d makes  $C[0,\infty)$  a separable metric space.
- (ii) Show that the Borel sigma-filed for d coincides with the cylinder sigma-field  $\mathcal{C}$ .

The distribution of X is a probability measure defined on C, the image of  $\mathbb{P}$  under the map  $\omega \mapsto X(\omega, \cdot)$ . For example, for a standard Brownian motion, the distribution is called **Wiener measure**, which I will denote by the symbol  $\mathbb{W}$ . In other words, if B is a standard Brownian motion, and at least if  $f: C[0, \infty) \to \mathbb{R}^+$  is a  $\mathbb{C} \setminus \mathcal{B}(\mathbb{R}^+)$ -measurable function, then

Note: "at least" is an invitation for you to extend the result to a larger set of functions

For fixed  $t \in \mathbb{R}^+$ ,  $\pi_t(x) := x(t)$  for  $x \in C[0, \infty)$ .

 $\mathbb{P}^{\omega}f(X(\omega,\cdot)) = \mathbb{W}^x f(x).$ 

Sometimes I will slip into old-fashioned terminology and call a real-valued (or extended-real-valued) function a *functional* if it is defined on a space of functions.

The stochastic process  $\{X_t : t \in \mathbb{R}^+\}$  defines on  $\Omega$  a *natural filtration* (sometimes called a raw filtration),

$$\mathcal{F}_t^\circ := \sigma\{X_s : 0 \le s \le t\} \qquad \text{for } t \in \mathbb{R}^+$$

with  $\mathcal{F}^{\circ}_{\infty} := \sigma\{X_s : s \in \mathbb{R}^+\}$ . Problem [2] shows that each  $\mathcal{F}^{\circ}_{\infty}$ -measurable random variable on  $\Omega$  can be expressed as a composition  $h(X(\omega, \cdot))$  with h

a C-measurable functional on  $C[0,\infty)$ . Moreover, if for each fixed  $\tau \in \mathbb{R}^+$ we define the stopping operator  $K_{\tau}: C[0,\infty) \to C[0,\infty)$  by

$$(K_{\tau}x)(t) = x(\tau \wedge t) \quad \text{for } t \in \mathbb{R}^+.$$

then each  $\mathcal{F}_t^{\circ}$ -measurable random variable on  $\Omega$  can be expressed as a composition  $h(K_t X(\omega, \cdot))$  with h a C-measurable functional on  $C[0, \infty)$ .

# 11.2 Decomposition of Brownian motion sample paths

Sometimes it is useful to have the underlying filtration on  $(\Omega, \mathcal{F}, \mathbb{P})$  built into the definition of the Brownian motion.

- <1> **Definition.** A process  $\{B_t : t \in \mathbb{R}^+\}$  with continuous sample paths is called a Brownian motion with respect to a filtration  $\{\mathcal{F}_t : t \in \mathbb{R}^+\}$  if
  - (i) B is adapted to the filtration
  - (ii) for each s < t, the increment  $B_t B_s$  is N(0, t s) distributed and is independent of  $\mathcal{F}_s$

**Remark.** It is not necessary to add the further requirement that the B process should have independent increments (as in the definition given in Chapter 1) because it follows directly from (ii).

Not surprisingly, a Brownian motion B in the sense of Chapter 1 is also a Brownian motion with respect to its natural filtration. As you will see in the next Section, it is useful that B is also a Brownian motion, in the sense of Definition <1>, with respect to a slightly larger, standard filtration.

For a fixed  $\tau \in \mathbb{R}^+$ , a generating class argument would show that the restarted process  $R_{\tau}B$ , defined by

$$R_{\tau}B(t) := B(\tau + t) - B(\tau) \qquad \text{for } t \in \mathbb{R}^+,$$

is also a Brownian motion, which is independent of  $\mathcal{F}_{\tau}$ . This property has a few useful consequences. Define the shift operator  $S_{\tau}$  by

$$(S_{\tau}x)(t) = \begin{cases} 0 & \text{for } 0 \le t < \tau \\ x(t-\tau) & \text{for } t \ge \tau \end{cases}$$

Then:

- (i) *B* has the same distribution as  $K_{\tau}B + S_{\tau}\widetilde{B}$ , where  $\widetilde{B}$  is a new standard Brownian motion that is independent of *B*.
- (ii) At least for each  $\mathcal{C}$ -measurable functional  $h: C[0,\infty) \to \mathbb{R}^+$ ,

$$\mathbb{P}(h(B) \mid \mathcal{F}_{\tau}) = \mathbb{W}^{x}h(K_{\tau}B + S_{\tau}x) \qquad \text{almost surely.}$$

That is, for each  $X \in \mathcal{M}^+(\Omega, \mathcal{F}_\tau)$  and each h as in (ii),

$$\mathbb{P}Xh(B) = \mathbb{P}^{\omega} \left( X(\omega) \mathbb{W}^x h(K_{\tau} B(\omega, \cdot) + S_{\tau} x) \right)$$

(iii) At least for each  $\mathcal{B}(\mathbb{R}) \otimes \mathcal{C}$ -measurable map  $f : \mathbb{R} \times C[0, \infty) \to \mathbb{R}^+$ , and each  $\mathcal{F}_{\tau}$ -measurable random variable Y,

$$\mathbb{P}f(Y,B) = \mathbb{P}^{\omega} \mathbb{W}^x f(Y, K_\tau B + S_\tau x)$$

See Pollard (2001, Chapter 9) for extensions of the these assertions the so-called strong Markov property for Brownian motion—when  $\tau$  is a stopping time.

#### 11.3 The Brownian filtration

Let  $\{\mathcal{F}_t^\circ : t \in \mathbb{R}^+\}$  be the natural filtration for a Brownian motion B (with continuous paths) defined on a complete probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ . Complete this filtration by adding the set  $\mathcal{N}$  of all  $\mathbb{P}$ -negligible subsets of  $\Omega$  to the generating class,

$$\mathfrak{F}_t = \sigma \left( \mathfrak{F}_t^\circ \cup \mathfrak{N} \right).$$

<2> Theorem. The process B is also a Brownian motion with respect to the completed filtration, which is standard.

**PROOF** The first assertion is easy to prove. Suppose s < t and  $F \in \mathcal{F}_s$ .

(i) Explain why there exists a set  $F^*$  in  $\mathcal{F}_s^\circ$  for which  $\mathbb{P}|F - F^*| = 0$ .

(ii) Show that

$$\mathbb{P}F^*f(B_t - B_s) = (\mathbb{P}F^*)(\mathbb{P}f(Z)) \quad \text{where } Z \sim N(0, t - s)$$

at least for each bounded  $\mathcal{B}(\mathbb{R})$ -measurable function f.

The standard property of the completed filtration requires a little more work. Consider an F in  $\mathcal{F}_{s+}$ .

- (iii) Let  $s_n = s + n^{-1}$ . Explain why there exist sets  $F_n \in \mathcal{F}_{s_n}$  and  $N_n \in \mathbb{N}$  such that  $|F F_n| = N_n$  for every n.
- (iv) Let  $F^* = \limsup_{n \to \infty} F_n$ . Show  $|F F^*| \le \bigcup_n N_n \in \mathbb{N}$  and  $F^* \in \mathfrak{F}_{s+}^{\circ}$ .
- (v) Suppose h is a bounded continuous functional and k is a bounded C-measurable functional, both defined on  $\mathfrak{X} := C[0, \infty)$ . Show that

 $\mathbb{P}k(K_sB)F^*h(R_{s_n}B) = \mathbb{P}k(K_sB)F^*\mathbb{W}h \quad \text{for each } n.$ 

- (vi) Let  $X := K_s B$  and  $Y := R_s B$ . Note that X and Y are independent. Let n tend to infinity in the previous step to deduce that  $\mathbb{P}k(X)F^*h(Y) = \mathbb{P}k(X)F^*\mathbb{P}h(Y)$ .
- (vii) Explain why  $F^* = g(X, Y)$  for some bounded, product measurable functional on  $\mathcal{X} \times \mathcal{X}$ .
- (viii) Define  $G(x) := \mathbb{W}^y g(x, y)$ . Explain why  $\mathbb{P}k(X)F^* = \mathbb{P}k(X)G(X)$ .
- (ix) Deduce that  $\mathbb{P}k(X)(F^* G(X))h(Y) = 0.$
- (x) Use a generating class argument to show the k(X)h(Y) in the previous equality can be replaced by f(X, Y), for a general bounded, product measurable f.
- (xi) By an appropriate choice of f, deduce that  $F \in \mathcal{F}_s$ .

From now on I will refer to the completed natural filtration as the **Brow**nian filtration. processes adapted to his filtration is not only standard, it also force Some important processes—local martingales—that are adapted to the Brownian filtration have two rather surprising properties: they have continuous sample paths and they can be represented as stochastic integrals. These two results are proved in the next Section.

# 11.4 Surprising properties for local martingales

Lect 23, Monday 12 April

<3> **Definition.** A cadlag process  $\{M_t : t \in \mathbb{R}^+\}$  is said to be a local martingale if there exist stopping times  $\{\tau_k : k \in \mathbb{N}\}$  with  $\sup_k \tau_k = \infty$  for which each  $M_{\wedge \tau_k} - M_0$  is a martingale. <4> Theorem. Every local martingale with respect to the Brownian filtration has almost all of its sample paths continuous. Consequently, every local martingale is also a locally square-integrable martingale.

PROOF Without loss of generality, assume the local martingale M starts with  $M_0 \equiv 0$ .

First consider the case of a cadlag martingale  $\{X_t : t \in \mathbb{R}^+\}$  with respect to the Brownian filtration. It is enough to show that almost all sample paths are continuous on each bounded interval [0, k]. For simplicity suppose k = 1.

- (i) Explain why X<sub>1</sub> can be expressed as f(B) for some C\B(ℝ)-measurable,
  W-integrable functional f on C[0,∞).
- (ii) If f is bounded and continuous (for the uccp metric), show that  $t \mapsto f(K_tB + S_ty)$  is continuous, for each fixed y in  $C[0,\infty)$ . Use the representation  $X_t = \mathbb{P}_t X_1 = \mathbb{W}^y f(K_tB + S_ty)$  almost surely, for each fixed t in [0,1], to show that  $X(\omega, \cdot)$  is continuous on [0,1] for almost all  $\omega$ .
- (iii) For the general f, show that there exists a sequence of bounded, continuous functionals  $\{f_n\}$  for which  $\mathbb{W}|f - f_n| \leq 4^{-n}$ . Hint: This approximation is a consequence of general properties of Borel probability measures defined on metric spaces.
- (iv) Let  $X_n$  be a version of the martingale  $\mathbb{P}_t f_n(B)$ , for  $0 \le t \le 1$ , with continuous sample paths. Show that  $\{|X_n(t) X(t)| : 0 \le t \le 1\}$  is a uniformly integrable submartingale with cadlag sample paths.
- (v) Define stopping times  $\tau_n := 1 \wedge \min\{t : |X_n(t) X(t)| \ge 2^{-n}\}$ . Show that

$$\mathbb{P}\{\sup_{0 \le t \le 1} |X_n(t) - X(t)| > 2^{-n}\} \le 2^n \mathbb{P}|X_n(\tau_n) - X(\tau_n)|$$
  
$$\le 2^n \mathbb{P}|X_n(1) - X(1)|$$
  
$$= 2^n \mathbb{P}|f_n(B) - f(B)|$$
  
$$< 2^{-n}$$

- (vi) Deduce that  $\sum_{n} \mathbb{P}\{\sup_{0 \le t \le 1} |X_n(t) X(t)| > 2^{-n}\} < \infty$  and hence  $\sup_{0 \le t \le 1} |X_n(t) X(t)| \to 0$  almost surely.
- (vii) Conclude that almost all sample paths of X are continuous.

(viii) Extend the argument to the case of a local martingale. Hint: If  $M_{\wedge \tau_k}$  has (almost all) continuous paths on [0, 1] for each k, and if  $\tau_k \uparrow \infty$ , what do you know about almost all paths of M?

The other surprising property is little more than an application of the Itô formula. To simplify the argument, work on a bounded interval. Remember that the submartingale  $\{B_t^2 : 0 \le t \le 1\}$  has Doléans measure  $\mu = \mathbb{P} \otimes \mathfrak{m}$ , where  $\mathfrak{m}$  denotes Lebesgue mesure on [0, 1].

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<5> **Theorem.** For each  $X \in \mathcal{L}^2(\Omega, \mathcal{F}_1, \mathbb{P})$ , where  $\{\mathcal{F}_t : 0 \leq t \leq 1\}$  is the Brownian filtration, there exists an  $H \in \mathcal{L}^2(\mu)$  such that  $X - \mathbb{P}X = H \bullet B_1$  almost surely.

**PROOF** (Sketch) Without loss of generality, suppose  $\mathbb{P}X = 0$ .

- (i) Explain why  $\mathcal{R} := \{H \bullet B_1 : H \in L^2(\mu)\}$  is a closed vector subspace of  $\mathcal{L}^2(\mathbb{P}, \mathcal{F}_1)$ .
- (ii) Let Z denote the component of X that is orthogonal to  $\mathcal{R}$ . That is,  $X = Z + K \bullet B_1$  for some  $K \in \mathcal{L}^2(\mu)$  and  $\mathbb{P}Z(H \bullet B)_1 = 0$  for all H in  $\mathcal{L}^2(\mu)$ . Show that  $\mathbb{P}Z = 0$ .
- (iii) Explain why it is enough to prove Z = 0 almost surely.
- (iv) Explain why it suffices to show  $\mathbb{P}Zf(B) = 0$  for all bounded, C-measurable functionals f on C[0, 1].
- (v) Explain why it suffices to consider functionals f that depend on B only through its increments  $Y_j = B_{t_{j+1}} B_{t_j}$  for a fixed set of times  $0 = t_0 < t_1 < \cdots < t_k = 1$ . That is, why is it enough to prove  $\mathbb{P}Zg(\mathbf{Y}) = 0$  for all bounded, measurable functions g on  $\mathbb{R}^k$ ?
- (vi) Invoke Problem [6] to show that it is enough to prove  $\mathbb{P}Z \exp(i\theta' \mathbf{Y}) = 0$  for all  $\theta$  in  $\mathbb{R}^k$ .
- (vii) Work with stochastic integral notation. Show that  $\theta' \mathbf{Y} = H \bullet B_1$ , where  $H := \sum_{j=0}^{k-1} \theta_j((t_j, t_{j+1})]$ .

- (viii) Show that  $H \bullet B$  has a deterministic quadratic variation process,  $A_t := [H \bullet B, H \bullet B]_t = \int_0^t H^2(s) \, ds.$
- (ix) Use Itô to show that

 $W_1 = 1 + i(WH) \bullet B_1$  where  $W_t := \exp(iH \bullet B_t + \frac{1}{2}A_t)$ .

(x) Deduce that

$$\exp(A_1/2)\mathbb{P}Z\exp(i\theta\cdot\mathbf{Y})=0$$

(xi) Are we done?

<6> Corollary. For each local martingale M adapted to the Brownian filtration there exists an H in  $loc \mathcal{L}^2(\mu)$  such that  $M_t = M_0 + H \bullet B_t$  for  $0 \le t \le 1$ .

PROOF Without loss of generality, suppose  $M_0 = 0$ . Define stopping times  $\tau_k := 1 \wedge \inf\{t : |M_t| \ge k\}.$ 

- (i) Why does  $M_{\wedge \tau_k}$  belong to  $\mathcal{M}_0^2[0,1]$ ?
- (ii) For each k, explain why there exists an  $H_k \in \mathcal{L}_2(\mu)$  such that

$$M_{t \wedge \tau_k} = \left( H_k((0, \tau_k)] \right) \bullet B_t \quad \text{for } 0 \le t \le 1.$$

- (iii) Deduce that  $(H_k((0, \tau_k])) \bullet B_1 = (H_{k+1}((0, \tau_k]) \bullet B_1 \text{ almost surely.})$
- (iv) Deduce that  $H_k((0, \tau_k]] H_{k+1}((0, \tau_k]] = 0$  almost everywhere  $[\mu]$ .
- (v) Show that the  $H_k$  processes can be pasted together to create an H in  $loc \mathcal{L}^2(\mu)$  for which  $M_t = H \bullet B_t$  almost surely.

construction for the  $loc\mathcal{M}_0^2[0,1]$ stochastic integral?

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**Remark.** Should I extend to general  $\mathcal{F}_1$ -measurable random variables, perhaps using the method of Dudley (1977), getting a representation  $Y_0 + H \bullet B_1$  with  $H \in \text{loc}\mathcal{H}_{\text{Bdd}}$ .

#### 11.5 Change of measure for Brownian motion

Let  $\{B_t : 0 \leq t \leq 1\}$  be a Brownian motion with respect to a standard filtration  $\{\mathcal{F}_t : 0 \leq t \leq 1\}$  on  $(\Omega, \mathcal{F}, \mathbb{P})$ . Write  $\mathcal{U}$  for its quadratic variation process,  $\mathcal{U}_t = t$ .

For each  $\alpha \in \mathbb{R}$ , the process

$$q_t = \exp\left(\alpha B_t - \frac{1}{2}\alpha^2 t\right) \quad \text{for } 0 \le t \le 1$$

is a nonnegative martingale, with  $\mathbb{P}q_t = \mathbb{P}q_0 = 1$ . Define a new probability measure  $\mathbb{Q}_{\alpha}$  on  $\mathcal{F}_1$  by specifying  $q_1$  to be its density with respect to  $\mathbb{P}$ . That is,  $\mathbb{Q}_{\alpha}X = \mathbb{P}(Xq_1)$ , at least for all bounded random variables X.

- Show that Q<sub>α</sub> is equivalent to P, in the sense that both measures have the same collection N of negligible sets.
- (ii) Show that  $\mathbb{Q}_{\alpha}X = \mathbb{P}(Xq_t)$  if X is  $\mathcal{F}_t$ -measurable. Explain why  $q_t$  is a Radon-Nikodym density for  $\mathbb{Q}_{\alpha}$  with respect to  $\mathbb{P}$  when both measures are restricted to  $\mathcal{F}_t$ .
- (iii) Define  $B_t^* := B_t \alpha t$ . For fixed s and  $t = s + \delta$ , define  $Y_1 := B_s$ ,  $Y_2 := B_t - B_s$ , and  $Y_3 := B_1 - B_t$ . For a fixed F in  $\mathcal{F}_s$  and  $\theta \in \mathbb{R}$ , show that

$$\begin{aligned} \mathbb{Q}_{\alpha}F \exp\left(i\theta(Y_2 - \alpha\delta)\right) \\ &= \mathbb{P}(Fq_s \exp\left((i\theta + \alpha)Y_2 - i\alpha\theta\delta + \alpha Y_3 - \frac{1}{2}\alpha^2(1-s)\right) \\ &= \mathbb{Q}_{\alpha}F \exp\left(-\frac{1}{2}\theta^2\delta\right) \end{aligned}$$

(iv) Deduce that, under  $\mathbb{Q}_{\alpha}$ , the  $B^*$  process is a standard Brownian motion.

#### 11.6 The Black-Scholes formula

Stock prices (in units so that  $S_0 \equiv 1$ ) are sometimes modeled by a continuous process driven by a Brownian motion, B, on [0, 1];

$$<7> \qquad S_t = \exp((\mu - \frac{1}{2}\sigma^2)t + \sigma B_t) \qquad \text{for } 0 \le t \le 1$$

for constants  $\sigma > 0$  (assumed known) and  $\mu$  (unknown). That is,

$$S_t = \psi_{\mu,\sigma}(B_t, \mathcal{U}_t) \quad \text{where } \psi_{\mu,\sigma}(x, y) := \exp(\sigma x + (\mu - \frac{1}{2}\sigma^2)y)$$
$$= 1 + \sigma S \bullet B_t + \mu S \bullet \mathcal{U}_t \quad \text{by the Itô formula.}$$

In more traditional notation,

$$dS_t = \sigma S_t \, dB_t + \mu S_t \, dt, \qquad \text{or} \qquad \frac{dS_t}{S_t} = \sigma \, dB_t + \mu \, dt.$$

Roughly speaking, the relative increments of S behave like the increments of a Brownian motion with drift  $\mu$ .

**Remark.** Throughout this Section I will ignore inflation. Equivalently, I could express the value of stock as a multiple of a bond price.

**Question:** Suppose X = f(S), with f a C-measurable functional on C[0, 1]. How much should one pay at time 0 in order to receive the amount X at time 1? Call this fair price  $C_0$ , a constant that is declared at time 0.

To answer the question I will first assume that  $\mu$  is zero, so that

$$S_t = \psi_{0,\sigma}(B_t, \mathcal{U}_t) = 1 + \sigma S \bullet B_t \quad \text{for } 0 \le t \le 1.$$

A change-of-measure will later restore the  $\mu$ . I will also assume  $\mathbb{P}X^2 < \infty$ . Think of  $\psi_{0,\sigma}$  as defining a continuous map  $\Psi_{\sigma}$  from C[0,1] to C[0,1],

$$\Psi_{\sigma}(x)(t) = \exp\left(\sigma x(t) - \frac{1}{2}\sigma^2 t\right) \quad \text{for } 0 \le t \le 1.$$

Then  $X = f(\Psi_{\sigma}B)$ , a C-measurable functional of the whole Brownian motion path. By Theorem  $\langle 5 \rangle$ , there exists a predictable process H, which is square-integrable with respect to the Doléans measure, such that

$$X = c + H \bullet B_1$$
 where  $c := \mathbb{P}X$ .

The process  $(\sigma S)^{-1}$  is locally bounded. If we integrate this process with respect to the semimartingale S we get, via <8>,

$$B = \frac{1}{\sigma S} \bullet S$$
 and  $X = c + K \bullet S_1$  where  $K_t := H_t / (\sigma S_t)$ 

Temporarily suppose K is of the form  $\sum_{j \leq k} h_j(\omega)((\tau_j, \tau'_j)]$  for stopping times  $\tau_j \leq \tau'_j$  and  $\mathcal{F}(\tau_j)$ -measurable random variables  $h_j(\omega)$ . Engage in the following trades:

- a) At time zero pay  $C_0$  in order to receive the random amount X at time 1.
- b) For j = 1, 2, ..., k, pay  $h_j$  at time  $\tau_j$ , at price  $S(\tau_j)$  per share, then sell the same shares at time  $\tau'_j$  at price  $S(\tau'_j)$  per share.

 $<\!\!8\!\!>$ 

The total profit at time 1 from the trading will be

$$X - C_0 + \sum_{j \le k} h_j \left( S(\tau'_j) - S(\tau_j) \right) = X - C_0 - K \bullet S_1 = c - C_0.$$

If  $c > C_0$  we would be very happy: pure profit without risk. If  $c < C_0$ , take the other side of each trade to make a profit of  $C_0 - c$  without risk. The set of trades in either case would be called an **arbitrage** scheme. Only if  $C_0 = c$ does the opportunity to make a riskless profit by arbitrage disappear. The fair price for X at time zero should be  $c = \mathbb{P}X$ .

Lect 25, Monday 19 April

It is traditional to interpret more general K processes as defining a limit of a sequence of discrete trades, or an idealized scheme for continuous trading, that would again force  $C_0 = \mathbb{P}X$  as the fair price.

For the arbitrage threat to be credible, the trading scheme K needs to be determined explicitly. I know how to find K if X is of the form  $X = g(L_1)$  where  $L_t := \log S_t = \sigma B_t - \frac{1}{2}\sigma^2$ . First note that

$$L_1 = L_t + \sigma(B_1 - B_t) - \frac{1}{2}(1 - t) = L_t + \gamma Z - \frac{1}{2}\gamma^2$$

where  $\gamma := \sigma \sqrt{1-t}$  and  $Z := (B_1 - B_t)/\sqrt{1-t} \sim N(0,1)$  if t > 0. Then the martingale  $X_t := \mathbb{P}_t X$  has the representation

$$X_t = G(L_t, \sigma\sqrt{1-t}) = G(\sigma B_t - \frac{1}{2}\sigma^2 t, \sigma\sqrt{1-t})$$

where

$$\begin{aligned} G(x,\gamma) &= \mathbb{P}g(x+\gamma Z - \frac{1}{2}\gamma^2) \\ &= \int_{-\infty}^{\infty} g(x+\gamma z - \frac{1}{2}\gamma^2)\phi(z)\,dz \quad \text{with } \phi(z) = \frac{\exp\left(-\frac{1}{2}z^2\right)}{\sqrt{2\pi}} \\ &= \gamma^{-1}\int_{-\infty}^{\infty} g(y)\phi\left(\frac{y-x - \frac{1}{2}\gamma^2}{\gamma}\right)\,dy \quad \text{ for } \gamma > 0 \end{aligned}$$

and G(x, 0) = g(x).

The final integral representation for G shows that  $X_t$  is a very smooth function of  $B_t$  and  $\mathcal{U}_t$  for all  $0 \leq t < 1$ . Apply the Itô formula.

$$X_t = C_0 + \sigma G_x \bullet B_t + W \bullet \mathcal{U}_t \quad \text{for } 0 \le t < 1,$$

where W is some locally bounded, predictable process involving  $G_{xx}$  and  $G_t$ . We don't need to calculate W explicitly, because the fact that  $X_t - C_0 - \sigma G_x \bullet B_t$  is a local martingale forces  $W \bullet \mathcal{U} = 0$  (Problem [5]). In particular,  $H = \sigma G_x$  is the predictable process for which  $X = C_0 + H \bullet B_t$  and  $C_0 = G(0, \sigma)$ . §11.6

**Remark.** Does it matter that we might have trouble defining  $H_1$ ? Does continuity of the sample paths of X take care of the problem?

You might try to explain why  $X_t$  is the fair price to pay at time t in order to receive X at time 1.

Now consider the case where  $\mu$  is unknown, possibly nonzero. Let  $\mathbb{Q}$  be the probability measure with density  $\exp(\alpha B_1 - \frac{1}{2}\alpha^2)$  with respect to  $\mathbb{P}$ , where  $\alpha = \mu/\sigma$ . From Section 5 we know that  $B_t^* = B_t - \alpha t$  is a Brownian motion under  $\mathbb{Q}$ . Also the process

$$S_t = \exp\left(\sigma B_t - \frac{1}{2}\sigma^2 t\right) = \exp\left(\sigma B_t^* + (\mu - \frac{1}{2}\sigma^2)t\right)$$

is a  $\mathbb{Q}$ -semimartingale with the distribution specified by <7>

The characterization of the stochastic integral in Theorem 8.5 should convince you that the representation  $X = C_0 + K \bullet S_1$  derived under  $\mathbb{P}$  is also valid under  $\mathbb{Q}$ . (By mutual absolute continuity of  $\mathbb{P}$  and  $\mathbb{Q}$ , uccp means the same thing under both measures.) We still have a trading strategy K, which does not depend on the unknown  $\mu$ , to enforce  $C_0$  as the fair price for X.

<10> **Example.** A European option gives the buyer the right to pay an amount K at time 1 in order to receive one unit of stock, regardless of the stock price at that time. If  $S_1 \leq K$  the option will be worthless; if  $S_1 > K$  it returns a profit of  $S_1 - K$ . In short, the option returns  $X = (S_1 - K)^+$  at time 1. That is, it corresponds to the function  $g(x) = (e^x - K)^+$ .

Calculate. Note that

 $\exp\left(x + \gamma z - \frac{1}{2}\gamma^2\right) \ge K \qquad \text{iff} \quad z \ge r := \left(\log K - x + \frac{1}{2}\gamma^2\right)/\gamma.$ 

For  $\gamma > 0$  we then get

$$\begin{aligned} G(x,\gamma) &= \int_{-\infty}^{\infty} g(x+\gamma z - \frac{1}{2}\gamma^2)\phi(z) \, dz \\ &= \int_{r}^{\infty} \exp\left(x+\gamma z - \frac{1}{2}\gamma^2\right)\phi(z) \, dz - K \int_{r}^{\infty}\phi(z) \, dz \\ &= e^x \int_{r}^{\infty}\phi(z-\gamma) \, dz - K \int_{r}^{\infty}\phi(z) \, dz \\ &= e^x \overline{\Phi}(r-\gamma) - K \overline{\Phi}(r) \end{aligned}$$

where  $\overline{\Phi}(t) := \mathbb{P}\{Z \ge t\}$  for  $Z \sim N(0, 1)$ . In particular,

$$C_0 = G(0,\sigma) = \overline{\Phi}\left(\frac{\log K - \frac{1}{2}\sigma^2}{\sigma}\right) - K\overline{\Phi}\left(\frac{\log K + \frac{1}{2}\sigma^2}{\sigma}\right)$$

This result will look more like the traditional Black-Scholes formula displayed by Steele (2001, Section 10.3) if you put his initial share price S equal to 1, take his interest rate r equal to zero, and use the fact that  $\overline{\Phi}(y) - \Phi(-y)$ .

# 11.7 Problems

- [1] Let  $\psi$  be a map from  $(\Omega, \mathcal{F})$  to  $C[0, \infty)$ .
  - (i) Show that  $\psi$  is  $\mathcal{F}\C$ -measurable if and only if  $\pi_t \circ \psi$  is  $\mathcal{F}\B(\mathbb{R})$ -measurable for each  $t \in \mathbb{R}^+$ .
  - (ii) Deduce that a stochastic process  $\{X_t : t \in \mathbb{R}^+\}$  with continuous sample paths defines an  $\mathcal{F}\$ C-measurable map from  $\Omega$  into  $C[0, \infty)$ .
- [2] Suppose X is a stochastic process with sample paths in  $C[0,\infty)$ . For each fixed t, define  $\mathcal{F}_t^{\circ} := \sigma\{X_s : 0 \le s \le t\}$ .
  - (i) Show that  $\mathcal{F}_t^{\circ}$  is the smallest sigma-field for which the map  $\omega \mapsto K_t X(\omega, \cdot)$  is  $\mathcal{F}_t^{\circ} \setminus \mathcal{C}$ -measurable.
  - (ii) Deduce (cf. Pollard 2001, Problem 2.3) that each  $\mathcal{F}_t^{\circ}$ -measurable random variable can be factorized as  $h(K_tX(\omega, \cdot))$  for some C-measurable functional  $h: C[0, \infty) \to \overline{\mathbb{R}}$ .
- [3] Suppose  $Z \in \mathbb{FV}_0 \cap \operatorname{loc} \mathcal{M}_0^2(\mathbb{R}^+)$  and Z has continuous sample paths. Show that  $Z_t = 0$  almost surely, for each t. Hint: Use the fact that [Z, Z] = 0to deduce that  $Z^2 = 2Z \bullet Z \in \operatorname{loc} \mathcal{M}_0^2(\mathbb{R}^+)$ . Find a sequence of stopping times  $\tau_k \uparrow \infty$  for which  $\mathbb{P}Z_{t \land \tau_k}^2 = 0$  for each t.
- [4] Suppose  $M \in \operatorname{loc}\mathcal{M}_0^2(\mathbb{R}^+)$  has continuous sample paths. Suppose  $A \in \mathbb{FV}_0$ also has continuous paths and  $M^2 - A \in \operatorname{loc}\mathcal{M}_0^2(\mathbb{R}^+)$ . Deduce that A = [M, M]. Hint: Apply Problem [3] to [M, M] - A.
- [5] Suppose  $W \in \text{loc}\mathcal{H}_{\text{Bdd}}$  is such that  $M_t := W \bullet \mathcal{U}_t$  is a local martingale. Use the fact that  $M^2 - [M, M]$  is a local martingale to deduce that M is indistinguishable from the zero process. Hint:  $[M, M] = W^2 \bullet [\mathcal{U}, \mathcal{U}] = 0$ .
- [6] Let X be an integrable random variable on  $(\Omega, \mathcal{F}, \mathbb{P})$  and  $Y = (Y_1, \ldots, Y_k)$ be a vector of random variables such that  $\mathbb{P}X \exp(i\theta' Y) = 0$  for all  $\theta = (\theta_1, \ldots, \theta_k)$  in  $\mathbb{R}^k$ . Show that  $\mathbb{P}(Xg(Y)) = 0$  for all bounded, measurable g by these steps.

(i) Let  $\phi_{\sigma}$  denote the  $N(0, \sigma^2 I_k)$  density. Show (cf. Pollard 2001, Section 8.2) that

$$\phi_{\sigma}(t) = (2\pi)^{-k} \mathfrak{m}^{\theta} \exp\left(-i\theta' t - \frac{1}{2}\sigma^{2}|\theta|^{2}\right)$$

where  $\mathfrak{m}$  denotes k-dimensional Lebesgue measure.

(ii) Suppose  $Z \sim N(0, \sigma^2 I_k)$  independently of (X, Y). For each continuous, real-valued h with compact support on  $\mathbb{R}^k$ , justify all the implicit appeals to Fubini to show that

$$\mathbb{P}Xh(Y+Z) = \mathbb{P}^{\omega}X(\omega)\mathfrak{m}^{z}h(Y(\omega)+z)\phi_{\sigma}(z)$$
  
=  $\mathbb{P}^{\omega}X(\omega)\mathfrak{m}^{u}h(u)\phi_{\sigma}(u-Y(\omega))$   
=  $\mathfrak{m}^{u}\mathfrak{m}^{\theta}h(u)(2\pi)^{-k}\mathbb{P}X\exp\left(-i\theta'(u-Y)-\frac{1}{2}\sigma^{2}|\theta|^{2}\right)$   
= 0

- (iii) Let  $\sigma$  tend to zero to deduce that  $\mathbb{P}Xh(Y) = 0$ .
- (iv) Use a lambda-space argument to extend to all bounded, measurable g.
- [7] Let X and Y be independent Brownian Motions.
  - (i) Show that both  $(X+Y)/\sqrt{2}$  and  $(X-Y)/\sqrt{2}$  are also Brownian Motions.
  - (ii) Deduce that [X, Y] = 0.

The next problem presents the standard example of a uniformly integrable local martingale that is not of class [D].

- [8] Let  $\boldsymbol{B} = (1+X,Y,Z)$  be a three-dimensional Brownian Motion started from  $\boldsymbol{u} = (1,0,0)$ . (The three processes X, Y, and Z are independent Brownian Motions started from zero.) Write  $\mathbf{x}$  for (x, y, z). Define  $f(\mathbf{x}) = 1/||\mathbf{x}||$  on  $\mathbb{R}^3 \setminus \{0\}$ . Define a process  $M(t) = 1/||\mathbf{B}(t)||$ .
- Better to start at origin, and work with distance to u?
- (i) Use the Multiprocess Itô Formula to show that  $M \in \text{loc}\mathcal{M}^2(\mathbb{R}^+)$ . Hint: Show that on the open region  $\mathbb{R}^3 \setminus \{0\}$  the function f is harmonic:

$$\frac{\partial^2 f}{\partial^2 x} + \frac{\partial^2 f}{\partial^2 y} + \frac{\partial^2 f}{\partial^2 z} = 0.$$

- (ii) Deduce that M is a positive supermartingale.
- (iii) Let  $\tau_k = \inf\{t : \|\boldsymbol{B}(t)\| \le 1/k\}$ . Show that  $M_{\wedge \tau_k} \in \mathcal{M}^2(\mathbb{R}^+)$ .
- (iv) Show that  $C_0 := \int \{ \|\mathbf{x}\| \le \frac{1}{2} \} \|\mathbf{x}\|^{-2} d\mathbf{x} < \infty.$

(v) Show that 
$$\mathbb{P}M(t)^2 \le C_0 \exp(-(8t)^{-1})t^{-3/2} + \mathbb{P}\left(8 \land \|\boldsymbol{B}(t)\|^{-2}\right).$$

- (vi) Show that  $\|\boldsymbol{B}(t)\|^2 \xrightarrow{\mathbb{P}} \infty$  as  $t \to \infty$ .
- (vii) Deduce that  $\sup_t \mathbb{P}M(t)^2 < \infty$  and  $\mathbb{P}M(t) \to 0$  as  $t \to \infty$ .
- (viii) Deduce that M is not a martingale, and hence M is not in class [D].

# 11.8 Notes

See Steele (2001, Chapter 10) and Chung and Williams (1990, Section 10.5) for slightly different ways to derive option prices by arbitrage arguments. I learned about the significance of semimartingales for option pricing from Harrison and Pliska (1981).

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