

[S_{indep}]**7. Independent normals**

Inequality <1> bounds the distance between the multinomial and multivariate normal models $\mathcal{M}$ and $\mathcal{N}$, where $\mathcal{N} := \{\mathbb{Q}_\theta : \theta \in \Theta\}$ with $\mathbb{Q}_\theta := N(n\theta, nV_\theta)$. Under $\mathbb{Q}_\theta$, the coordinates are dependent variables, whereas the increments of Nussbaum's white noise model are independent, with variances that do not depend on θ .

Carter completed his rederivation of Nussbaum's result by a sequence of steps leading from $\mathcal{N}$ to the white noise model. (He also presented analogous arguments for randomizing the white noise model to approximate $\mathcal{N}$, which I will not discuss. The ideas are almost the same for both directions.) He compared $\mathcal{N}$ with the white noise via two intermediate models:

(i) $\mathcal{N}_{\text{indep}} := \{\mathbb{N}_\theta : \theta \in \Theta\}$, where $\mathbb{N}_\theta = \otimes_{i \leq m} N(n\theta_i, n\theta_i)$.

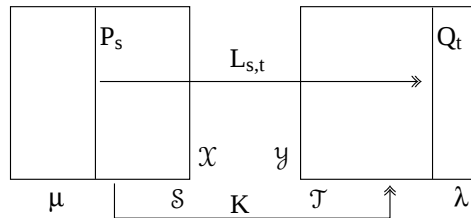
(ii) $\mathcal{N}_{\text{stabil}} := \{\tilde{\mathbb{N}}_\theta : \theta \in \Theta\}$, where $\tilde{\mathbb{N}}_\theta = \otimes_{i \leq m} N(\sqrt{n\theta_i}, 1/4)$.

Finally, he used the random vectors with distribution $\tilde{\mathbb{N}}_\theta$ to obtain (by interpolation) processes with continuous paths, which are close to the white noise processes.

I will discuss the interpolation in Section 9, the comparison of $\mathcal{N}_{\text{indep}}$ and $\mathcal{N}_{\text{stabil}}$ in Section 8, and the comparison of $\mathcal{N}$ and $\mathcal{N}_{\text{indep}}$ in the current Section.

Think of each $\mathbb{Q}_\theta$ as a probability measure on $\mathcal{X} := \mathbb{R}^m$ and each $\mathbb{N}_\theta$ as a probability measure on $\mathcal{Y} := \mathbb{R}^m$. Under $\mathbb{Q}_\theta$, the sum $s := \sum_{i \leq m} x_i$ has a distribution μ that is degenerate at n . Under $\mathbb{N}_\theta$, the sum $t := \sum_{i \leq m} y_i$ has distribution $\lambda := N(n, n)$. Moreover, under $\mathbb{N}_\theta$, the conditional distribution of y given t is $\mathbb{Q}_{\theta,t} := N(t\theta, nV_\theta)$. Note that $\mathbb{Q}_{\theta,n} = \mathbb{Q}_\theta$. The models $\mathcal{N}_{\text{indep}}$ from $\mathcal{N}$ have the same form of conditional distribution given the totals; they differ only in the distributions of the sums.

We are again in the situation covered by Lemma <5>, with $P_s := \mathbb{Q}_{\theta,s}$ and $Q_t := \mathbb{Q}_{\theta,t}$. Under μ , only the value $s = n$ is relevant, but under λ we need to consider all values of t .



We can take K_x as the $N(n, n)$ distribution for all x . (Of course, only the value $x = n$ is really needed.) We must choose the randomization $L_{s,t}$ to control

$$\|L_{n,t}N(n\theta, nV_\theta) - N(t\theta, nV_\theta)\|.$$

REMARK. It might seem that we could take $L_{n,t}$ as the identity map, since the t should be close to n with high probability under λ . However, closeness of means would not suffice, because V_θ is singular: if $t \neq n$ then $\|\mathbb{Q}_{\theta,t} - \mathbb{Q}_{\theta,n}\| = 2$. We need to match the means.

Choose $L_{n,t}$ as the map that corresponds to multiplication of a random vector by the constant t/n . That is, take $L_{n,t,x}$ as the point mass at tx/n . Then take

$$\rho(n, t) := \|N(t\theta, (t^2/n)V_\theta) - N(t\theta, nV_\theta)\| = \|N(0, (t/n)^2 nV_\theta) - N(0, nV_\theta)\|.$$

In general, for any $m \times m$ covariance matrix W and any constant c , both the $N(0, W)$ and the $N(0, c^2 W)$ are image measures of products of independent normals under the linear map $W^{1/2}$. Total variation distance can only be decreased by such a map. Thus

$$\begin{aligned} \|N(0, \bar{t}^2 nV_\theta) - N(0, nV_\theta)\|^2 &\leq \|N(0, \bar{t}^2 I_m) - N(0, I_m)\|^2 \quad \text{where } \bar{t} := t/n \\ &\leq 4mH^2(N(0, 1), N(0, \bar{t}^2)) \\ &\leq 8m(\bar{t}^2 - 1)^2 \quad \text{by Problem [1].} \end{aligned}$$

Under K_n , the random variable $\bar{t}$ has a $N(1, 1/n)$ distribution. Thus

$$(\mu \otimes K\rho(s, t))^2 \leq 8m\mathbb{P}((1 + N(0, 1/n))^2 - 1)^2 \leq Cm/n,$$

for some constant C .

It follows that $\delta(\mathcal{N}, \mathcal{N}_{\text{indep}})$ is bounded by a constant multiple of $\sqrt{m/n}$, which is smaller than the bound in <1>. A similar argument gives a similar bound for $\delta(\mathcal{N}_{\text{indep}}, \mathcal{N})$. When combined with <1>, these bounds give, for some new constant C ,

$$\Delta(\mathcal{M}, \mathcal{N}_{\text{indep}}) \leq C \frac{m \log m}{\sqrt{n}} \quad \text{provided } \sup_{\theta \in \Theta} \frac{\max_i \theta_i}{\min_i \theta_i} \leq C_\Theta < \infty.$$

[§sqrt] 8. Variance stabilizing transformations

Each $\mathbb{N}_\theta$ is a product measure, $\otimes_i N(n\theta_i, n\theta_i)$, but the variances still depend on θ . To remove this dependence, Carter (following the lead of Nussbaum) applied the classical method for variance stabilization.

Suppose X has a $N(\mu, \mu)$ distribution for a large positive μ . Let g be a smooth, increasing function. Then the random variable $Y = g(X)$ is approximated by $g(\mu) + g'(\mu)(X - \mu)$, which has a normal distribution with mean $g(\mu)$ and variance $\mu g'(\mu)^2$. If we choose g so that $g'(\mu)$ is proportional to $1/\sqrt{\mu}$, then the variance of the approximation will not depend on μ .

Clearly we should choose g so that $g(x) = \sqrt{x}$, at least for large positive x . For example, we could define $g(x) = \sqrt{x}\{x \geq 1\} + h(x)\{x < 1\}$, for an arbitrary smooth h that makes g behave smoothly at $x = 1$. Of course, the behavior for small x should be irrelevant—because the important contributions come from a region near μ —but it is inconvenient to have to worry about the possibility of taking the square root of a negative value for X .

If we apply the transformation g to each coordinate, we should obtain a new distribution close (under $\mathbb{N}_\theta$) to $\tilde{\mathbb{N}}_\theta := \otimes_i N(\sqrt{n\theta_i}, 1/4)$. More formally, we have a map $G : \mathbb{R}^m \rightarrow \mathbb{R}^m$ for which we hope $\|G\mathbb{N}_\theta - \tilde{\mathbb{N}}_\theta\|$ is small for all θ in Θ .

Using Taylor expansions, after separating out contributions from the lower tails, Carter was able to derive a bound on $D(g(N(\mu, \mu)) \| N(\sqrt{\mu}, 1/4))$. This bound gives the desired control over total variation distance between the product measures. And so on. In short, Carter showed that $\Delta(\mathcal{N}_{\text{indep}}, \mathcal{N}_{\text{stabil}})$ is also small enough to be absorbed into the bound from <12>, leading to

$$\text{carter3} \quad <13> \quad \Delta(\mathcal{M}, \mathcal{N}_{\text{stabil}}) \leq C \frac{m \log m}{\sqrt{n}} \quad \text{provided} \quad \sup_{\theta \in \Theta} \frac{\max_i \theta_i}{\min_i \theta_i} \leq C_\Theta < \infty.$$

for some new constant C .

Carter's method is satisfactory, but I feel it would be more elegant if we could appeal to some general result about variance stabilization rather than having to derive a special case. I outline below what I would like to include in the final version of these Paris notes. I invite elegant solutions from the audience before the end of May.

The general problem

Let X be a random variable whose distribution P has density f with respect to Lebesgue measure on $\mathbb{R}$. Let g be a smooth, increasing function on $\mathbb{R}$. Suppose f concentrates most of its mass near a value μ . The classical delta-method then asserts that the distribution of $g(X)$ should be close to the distribution Q of $Z := g(\mu) + g'(\mu)(X - \mu)$, which has density

$$q(z) = \frac{1}{g'(\mu)} f\left(\mu + \frac{z - g(\mu)}{g'(\mu)}\right)$$

with respect to Lebesgue measure.

For our purposes we need the distributions close in the total variation sense. More precisely, it will be useful to have a good bound for

$$H^2(g(P), Q) = H^2(P, g^{-1}(Q)).$$

The measure $g^{-1}(Q)$, which is the distribution of $g^{-1}(Z)$, has a density

$$f_0(x) := q(g(x)) g'(x) = \frac{g'(x)}{g'(\mu)} f(\kappa(x)) \quad \text{where} \quad \kappa(x) := \mu + \frac{g(x) - g(\mu)}{g'(\mu)}.$$

Notice that κ is an increasing function for which $\kappa(x) = x + o(|x - \mu|)$ near μ .

Write $\xi(x)$ for $\sqrt{f(x)}$ and $\gamma(x)$ for $\sqrt{g'(x)/g'(\mu)}$. Then

$$\text{hell.delta} \quad <14> \quad H^2(P, g^{-1}(Q)) = \int (\xi(x) - \gamma(x)\xi(\kappa(x)))^2 dx$$

REMARK. I have the feeling that there should be a neat general bound for the right-hand side of <14>, perhaps something involving $\int \dot{\xi}(x)^2 dx$. One should be able to bound crudely the contributions from outside some neighborhood U of μ . For the delta-method to work, the derivative $g'(x)$ must stay close to $g'(\mu)$ on the neighborhood. Perhaps a tractable expression involving $(x - \mu)g''(x)$ could be found. That suggests we could hope for a final bound involving something like $\sup_{x \in U} |g''(x)|$ and $\int (x - \mu)^2 f(x) dx$. I would start by splitting <14> into a sum of two terms, obtained by adding and subtracting $\xi(x)\gamma(x)$ inside the square.

[§interpolate]

9. Intepolation of increments

The problem solved by Nussbaum (1996) involves the asymptotic equivalence between $\{P_f^n : f \in \mathcal{F}\}$ and the model $\mathbb{W}_n := \{\mathbb{W}_{n,f} : f \in \mathcal{F}\}$, where $\mathcal{F}$ is a family of smooth density functions on $[0, 1]$. That is, the first experiment corresponds to samples of size n from the distribution P_f with density f with respect to Lebesgue measure m on $[0, 1]$, and $\mathbb{W}_{n,f}$ denotes the probability measure on $C[0, 1]$ defined by the white noise process $2\sqrt{n}F_f(t) + W_t$ for $0 \leq t \leq 1$, where the drift function is defined as

$$\text{drift.f} \quad <15> \quad F_f(t) = \int_0^t \sqrt{f(x)} dx \quad 0 \leq t \leq 1.$$

The process $\{W_t : 0 \leq t \leq 1\}$ is a Brownian motion with continuous sample paths. started from $W_0 \equiv 0$.

With Carter's approach, we discretize the observations from P_f by grouping them into m disjoint cells, intervals of length $1/m$, thereby defining a vector of counts with a multinomial distribution, $\mathcal{M}(n, \theta)$, where the vector $\theta := (\theta_1, \dots, \theta_m)$ actually depend on the underlying density. That is,

$$\text{theta.f} \quad <16> \quad \theta_i := \int_{J_i} f(x) dx \quad \text{for } i = 1, \dots, m \quad \text{where } J_i := \left(\frac{i-1}{n}, \frac{i}{n} \right].$$

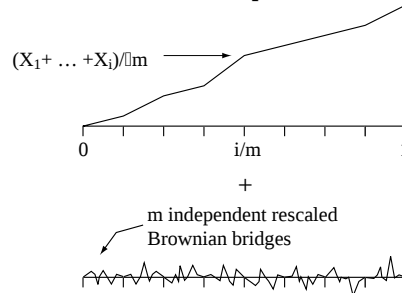
REMARK. Perhaps I should write θ_f to indicate the dependence on f when discussing the application of Carter's general inequality <1> to the Nussbaum problem.

From <16> we have

$$\text{theta.approx} \quad <17> \quad n\theta_i \approx (n/m) f(i/m) \quad \text{for } i = 1, \dots, m.$$

The measure $\tilde{\mathbb{N}}_\theta$ corresponds to independent observations $N(\sqrt{n\theta_i}, 1/4)$. To simplify the notation, I will multiply the observations by 2, making $\mathbb{N}_\theta$ correspond to independent random variables $X_i \sim N(2\sqrt{n\theta_i}, 1)$.

We need a randomization (not depending on f) that will build a process with a distribution close to $\mathbb{W}_{n,f}$, starting from $\{X_i : i = 1, \dots, m\}$. The obvious method is to interpolate between the partial sums of the X_i 's, to build a piecewise linear continuous function with value $(X_1 + \dots + X_m)/\sqrt{m}$ at i/m , for $i = 0, 1, \dots, m$. On each linear segment we then add the independent, rescaled Brownian bridges.



In fact, this procedure gives us a white noise with drift. To understand why, it helps to write $X_i = 2\sqrt{n\theta_i} + \xi_i$, where $\xi_1, \dots, \xi_m$ are independent $N(0, 1)$

variables, and express the Brownian bridges as Gaussian process whose covariances are determined by the measures

$$\text{nui} \quad <18> \quad \nu_i = \text{uniform distribution on } J_i, \text{ for } i = 1, \dots, m.$$

Notice that $m = \sum_{i \leq m} \nu_i / m$. Take B_i as the centered Gaussian process with continuous paths and covariances

$$\text{BB.cov} \quad <19> \quad \text{cov}(B_i(s), B_i(t)) = \nu_i[0, s \wedge t] - \nu_i[0, s]\nu_i[0, t] \quad \text{for } 0 \leq s, t \leq 1.$$

The interpolated process is then $X(t) := \sum_{i \leq m} X_i \nu_i[0, t] / \sqrt{m}$ and the randomization is given by the Gaussian process $\sum_{i \leq m} B_i(t) / \sqrt{m}$. That is, we hope to approximate $\mathbb{W}_{n,f}$ by the distribution of the process

$$Z_n(t) := m^{-1/2} \sum_{i \leq m} \left((2\sqrt{n\theta_i} + \xi_i) \nu_i[0, t] + B_i(t) \right).$$

The gaussian process $B_i(t) + \xi_i \nu_i[0, t]$ has covariance $\nu_i[0, s \wedge t]$. The standardized sum of such processes has covariance

$$m^{-1} \sum_{i \leq m} \nu_i[0, s \wedge t] = m[0, s \wedge t] = s \wedge t.$$

That is, the standardized sum is a Brownian motion. The process Z_n has the same distribution as

$$W_t + m^{-1/2} \sum_{i \leq m} 2\sqrt{n\theta_i} \nu_i[0, t] \quad \text{for } 0 \leq t \leq 1.$$

The slope of the drift is a step function, taking values

$$m^{-1/2} 2\sqrt{n\theta_i} m \approx 2\sqrt{nf(i/m)} \quad \text{for } x \in J_i$$

The approximation comes from <17>.

Thus we are left with the task of bounding the total variation distance between $\mathbb{W}_{n,\tilde{f}}$ and $\mathbb{W}_{n,f}$, where $\tilde{f}$ is a step function that approximates f . In fact, it is not hard to find an explicit expression for $\|\mathbb{W}_{n,\tilde{f}} - \mathbb{W}_{n,f}\|$ involving the $\mathcal{L}^2(m)$ distance between the square roots of f and $\tilde{f}$. By such means, we could calculate a bound on $\delta(\mathcal{N}_{\text{stabil}}, \mathcal{W}_n)$. However, there is a problem.

The method outlined in the preceding Sections is intended to reproduce Nussbaum's result only for the case where f has a bounded derivative that satisfies a Lipschitz condition of order $\alpha - 1$, for some $1 < \alpha \leq 2$. (See the next Chapter for refinements to cover $1/2 < \alpha \leq 1$.) For such f , the step function approximation is too crude to establish the desired bound for $\delta(\mathcal{N}_{\text{stabil}}, \mathcal{W}_n)$. Instead, we must use an interpolation that corresponds to a smoother approximating $\tilde{f}$.

As Carter showed, such an improvement is easily achieved. He replaced the uniform distributions by a family of probability distributions with continuous densities with respect to m , for which it is still true that $m = \sum_{i \leq m} \nu_i / m$. The new interpolating functions $\nu_i[0, t]$ lead a better approximation for f , by taking advantage of its assumed smoothness. Very elegant.

REMARK. Undoubtedly the improved method corresponds to some simple wavelet fact. I would be pleased to have the connection explained to me.